

## Common Fixed Point Theorem in Complete Metric Space With Weakly Compatible Maps

Jagrithi Chandra<sup>1</sup> & Sanjay Sharma<sup>2</sup>

<sup>1</sup>Department of Mathematics, Parthivi College of Engg. & Management (C.G.), India

<sup>2</sup>Department of Mathematics, Bhilai Institute of Technology, Durg (C.G.) 491001, India

**ABSTRACT:** In this paper the concept of implicit relations & complete metric space which generalizes the result of Brian Fisher by a weaker condition such as weakly compatibility instead of compatibility & contractive modulus instead of continuity of maps.

**KEYWORDS:** Common fixed point, Complete metric space, Weakly compatible maps, Contractive modulus MATHS

**SUBJECT CLASSIFICATION:** 47H10, 54H25.

1. INTRODUCTION : the study of common fixed point of mappings satisfying contractive type conditions has been very active field of research activity during last three decades. Brian Fisher [1] proved an important common fixed point theorem In 1922m the Polish mathematician, Banach , proved a theorem which ensures under appropriate conditions, the existence & uniqueness of a fixed point. His result is called Banach fixed point theorem or the Banach contraction principle. This theorem provides a technique for solving a variety of applied problems in mathematical science & engineering. Many authors have extended, generalized & improved Banach fixed point theorem in different ways. In[2] Jungck introduced more generalized commuting mappings, called compatible mappings which are more general than commuting & weakly commuting mappings.

The concept of the commutativity has generalized in several ways. For this sessa [6] has introduced the concept of weakly commuting and Gerald Jungck 7 Rhoades [4] introduced notion of weakly compatible & showed that compatible maps are weakly compatible but not conversely.

### 2. PRELIMINARIES :

Definition 2.1:- A sequence  $\{x_n\}$  in a metric space  $(X, d)$  is said to be convergent to a point  $x \in X$ , denoted by  $\lim_{n \rightarrow \infty} x_n = x$  if  $\lim_{n \rightarrow \infty} d(x_n, x_m) = 0$ .

Definition 2.2:- A sequence  $\{x_n\}$  in a metric space  $(X, d)$  is said to be Cauchy sequence if  $\lim_{t \rightarrow \infty} (x_n, x_m) = 0$  for all  $n, m > t$

Definition 2.3:- A metric space  $(X, d)$  is said to be complete if every Cauchy sequence in  $X$  is convergent.

Definition 2.4:- Let  $f$  &  $g$  be two self maps defined on a set, then  $f$  &  $g$  are said to be weakly compatible if they commute at coincidence points, i.e., if  $fu = gu$  for some  $u \in X$  then  $fgu = gfu$ .

Definition 2.5:- Let  $f$  &  $g$  be mapping from a metric space  $(X, d)$  into itself. The mapping  $f$  &  $g$  are said to be compatible if  $\lim_{n \rightarrow \infty} d(fgx_n, gfx_n) = 0$  whenever  $\{x_n\}$  is a sequence in  $X$  such that  $\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t$  for some  $t \in X$

Definition 2.6:- A pair  $(f, g)$  of self-mappings of a metric space is said to be semi-compatible  $\lim_{n \rightarrow \infty} fgx_n = gx$ , whenever  $\{x_n\}$  is a sequence in  $X$  such that  $\lim_{n \rightarrow \infty} fx_n = gx_n = x$

Definition 2.7:- Let  $f$  &  $g$  be two self-maps on a set  $X$ . Maps  $f$  &  $g$  are said to be commuting if  $fgx = gfx$  for all  $x \in X$

Definition 2.8:- Let  $f$  &  $g$  be two self-maps on a set  $X$ . If  $fx = gx$ , for some  $x$  in  $X$  then  $x$  is called coincidence of  $f$  &  $g$ .

Definition 2.9:- A function  $\phi : [0, \infty) \rightarrow [0, \infty)$  is said to be contractive modulus if  $\phi : [0, \infty) \rightarrow [0, \infty)$  &  $\phi(t) < t$  for  $t > 0$ .

Definition 2.10:- A real valued function  $\phi$  defined on  $X \subseteq \mathbb{R}$  is said to be upper semi continuous if  $\lim_{n \rightarrow \infty} \phi(x_n) \leq \phi(x)$  for every sequence  $\{x_n\} \in X$  with

$$x_n \rightarrow x \text{ as } n \rightarrow \infty$$

### 3. MAIN RESULT

#### 3.1 Implicit Relations :

Let  $F^*$  be the set of real functions  $F(t_1, t_2, \dots, t_5) : [0, \infty]^5 \rightarrow [0, \infty]$  satisfying

- (F<sub>1</sub>)  $F$  is non increasing in variables  $t_4$  &  $t_5$
- (F<sub>2</sub>) There is an  $h_1 > 0$  &  $h_2 > 0$  such that  $h = h_1 h_2 < 1$  & if  $u \geq 0, v \geq 0$  satisfy
  - (F<sub>a</sub>)  $u \leq F(v, u, v, u+v, 0)$  then we have  $u \leq h_1 v$  & if  $u \geq 0, v \geq 0$  satisfy
  - (F<sub>b</sub>)  $u \leq F(v, u, v, 0, u+v)$  then we have  $u \leq h_2 v$
- (F<sub>3</sub>) If  $u \geq 0$  is such that  $u \leq F(0, 0, u, u, 0)$  then  $u = 0$

#### 3.2 Fixed Point Theorem:

Let  $P, Q, S$  &  $T$  are four self mappings of a complete metric space  $(X, d)$  satisfying the following conditions

- (a)  $P(X) \subseteq T(X), Q(X) \subseteq S(X)$
- (b)  $d(Px, Qy) \leq F(d(Sx, Ty); d(Sx, Px); d(Sx, Qy); d(Ty, Qy); d(Px, Ty))$   
 For all  $x$  &  $y$  in  $X$  where  $f \in F^*$

Then  $P, Q, S$  &  $T$  have unique common fixed point  $z$  in  $X$ . Further  $z$  is the unique common fixed point of  $P$  &  $S$  & of  $Q$  &  $T$

Proof: Suppose  $x_0 \in X$

Since  $P(X) \subset T(X), Q(X) \subset S(X)$

We can choose  $x_n, x_{n+1}, x_{n+2}$  such that

$$Px_n = Tx_{n+1} \text{ \& } Qx_{n+1} = Sx_{n+2}, n = 0, 1, 2, 3, \dots$$

Using (b) we have

$$\begin{aligned} d(Px_n, Qx_{n+1}) &\leq F(d(Sx_n, Tx_{n+1}); d(Sx_n, Px_{n+1}); d(Tx_{n+1}, Qx_{n+1}); d(Sx_n, Qx_{n+1}); d(Px_n, Tx_{n+1})) \\ &= F(d(Qx_{n-1}, Px_n); d(Qx_{n-1}, Px_n); d(Px_n, Qx_{n+1}); d(Qx_{n-1}, Qx_{n+1}); 0) \\ &\leq F(d(Px_n, Qx_{n-1}); d(Px_n, Qx_{n-1}); d(Px_n, Qx_{n+1}); d(Qx_{n-1}, Qx_{n+1}); 0) \\ &\leq F(d(Px_n, Qx_{n-1}); d(Px_n, Qx_{n-1}); d(Px_n, Qx_{n+1}); d(Px_n, Tx_{n-1}); d(Px_n, Qx_{n+1})) \end{aligned}$$

Thus by property (F<sub>a</sub>)

$$d(Px_n, Qx_{n+1}) \leq h_1 d(Px_n, Qx_{n-1})$$

Similarly,  $d(Qx_{n+1}, Px_n) \leq h_2 d(Px_{n-2}, Qx_{n-1})$

Therefore,  $d(Px_n, Qx_{n+1}) \leq h d(Px_{n-2}, Qx_{n-1})$

From this we conclude that  $d(Px_n, Qx_{n+1}) \leq h^n d(Px_0, Qx_1)$

$$d(Qx_{n+1}, Px_n) \leq h_2 h_1^n d(Qx_0, Px_1) \text{ for } n=1, 2, \dots$$

Since  $h < 1$  the sequence  $\{Px_0, Qx_1, Px_2, \dots, Qx_{n-1}, Px_n, Qx_{n+1}, \dots\}$  is a Cauchy sequence

Since  $(X, d)$  is a complete metric space this sequence has a limit  $z$  in  $X$  the consequences

$$\{Px_n\} = \{Tx_{n+1}\} \text{ \& } \{Qx_{n+1}\} = \{Sx_{n+2}\} \text{ converge to the point } z$$

We suppose that the mapping  $S$  is continuous, so that the sequences  $\{S^2x_n\}$  &  $\{SPx_n\}$  converge to the point  $Sz$ . Since  $P$  &  $S$  are weakly commute, we have

$$d(SPx_n, PSx_n) \leq d(Sx_n, Px_n)$$

so that the point  $\{PSx_n\}$  converges to the point  $Sz$ .

Using (b), we have

$$d(PSx_n, Qx_{n+1}) \leq F(d(S^2x_n, Tx_{n+1}); d(S^2x_n, PSx_n); d(Tx_{n+1}, Qx_{n+1}); d(S^2x_n, Qx_{n+1}); d(PSx_n, Tx_{n+1}))$$

By letting  $n \rightarrow \infty$ , we get

$$d(Sz, z) \leq F(d(Sz, z); 0; d(Sz, z); d(Sz, z))$$

Therefore by property (F<sub>3</sub>), we get  $d(Sz, z) = 0$  i.e.,  $Sz = z$

Again by using (b), we have

$$d(Pz, Qx_{n+1}) \leq F(d(Sz, Tx_{n+1}); d(Sz, Pz); d(Tx_{n+1}, Qx_{n+1}); d(Sz, Qx_{n+1}); d(Pz, Tx_{n+1}))$$

By letting  $n \rightarrow \infty$ , we get

$$d(Pz, z) \leq F(0; d(z, Pz); 0; 0; d(Pz, z))$$

Therefore by property (F<sub>3</sub>), we get  $d(Pz, z) = 0$  i.e.,  $Pz = z$

Since  $P(X) \cap T(X)$  there is a point  $y$  in  $X$  such that  $Ty = z$

Therefore by (b) , we have

$$d(z, Qz) = d(Pz, Qy) \leq F(d(Sz, Ty); d(Sz, Pz); d(Ty, Qy); d(Sz, Qy); d(Pz, Tz) )$$

so that  $d(z, Qz) \leq F(0; 0; d(z, Qy); d(z, Qy); 0)$

Therefore by property  $(F_3)$ , we get  $d(z, Qz) = 0$  i.e.,  $Qz = z$

Since  $Q$  &  $T$  are weakly commute , we have

$$d(Qz, Tz) = d(QTy, TQy) \leq d(Tz, Qy) = 0$$

Thus  $Qz = Tz$  & so that by (b), we have

$$\begin{aligned} d(z, Qz) = d(Pz, Qz) &\leq F( d(Sz, Tz); d(Sz, Qz); d(Tz, Qz); d(Sz, Qz); d(Pz, Tz) ) \\ &= F( d(z, Qz); d(z, z); d(Qz, Qz); d(z, Qz); d(z, Qz) ) \\ &= F( d(z, Qz); 0; 0; d(z, Qz); d(z, Qz) ) \end{aligned}$$

Therefore by property  $(F_3)$  , we get  $d(z, Qz) = 0$  i.e.,  $Qz = z$  i.e.,  $z = Qz = Tz$

Since  $Sz = Pz = z$ , we get  $z = Qz = Tz = Sz = Pz$

Thus  $z$  is a common fixed point of  $P, Q, S$  &  $T$

On the other way the proof is similar if mapping  $T$  is continuous.

Now if we consider that the mapping  $P$  or  $Q$  is continuous, in the similar way we can prove that  $z$  is a common fixed point of  $P, Q, S$  &  $T$ .

#### REFERENCES:

- [1] B.Fisher, Common Fixed Point of Four Mappings, Bull. Inst. of Math. Academia Sinicia 11(1983), 103-113.
- [2] G. Jungck, Compatible mappings & common fixed points, Internet. I. Math & Math. Sci. 9(1986), 771-779.
- [3] J. Matkowski, Fixed point theorems for mappings with a contractive iterate at a point, Proc. Amer.Math. Soc., 62(2) (1977), 344-348.
- [4] G. Jungck & B.E. Rhoades, Fixed point for set valued Functions without Continuity, Indian J. Pure Appl., 29(3) (1988), 227-238.
- [5] S. Rezapour & R. Hambarani, Some notes on the paper: Cone metric spaces and fixed point theorems of contractive mappings, Journal of Mathematical Analysis & Applications, 345(2)(2008), 719-724.
- [6] V. Popa, A general fixed point theorem for four weakly compatible mappings, satisfying an Implicit relation, Filomat 19(2005), 45-51.
- [7] V. Srinivas & R. Uma Maheshwar Rao, A Common Fixed Point theorem for Four Selfmaps, The Mathematics Education Vol. XL, No. 2 June(2006), 99-104.
- [8] S. Sessa “ On a Weak Commutativity Condition of Mapping in a Fixed Point Considerations, Publ. Inst. Math. Debre., 32(1982), 149-153.
- [9] M. Aamri & D. El. Moutawakil, Some new common fixed point theorems under strict Contractive conditions, J. Math. Anal. Appl., 270(2002), 181-188.
- [10] M.Imdad, Santosh Kumar & M.S. Khan, Remarks on fixed point theorems satisfying Implicit relations, Radovi Math., 11(2002), 135-143.